

## Q Learning Implementation

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### 1 Introduction

Reinforcement learning is a methodology focusing on training algorithms using a system of reward and punishment. And Q-Learning is an algorithm which produces a Q table that an agent uses to find the best action to take given a state. Our project was to develop a game which uses Q-Learning methods to win the game.

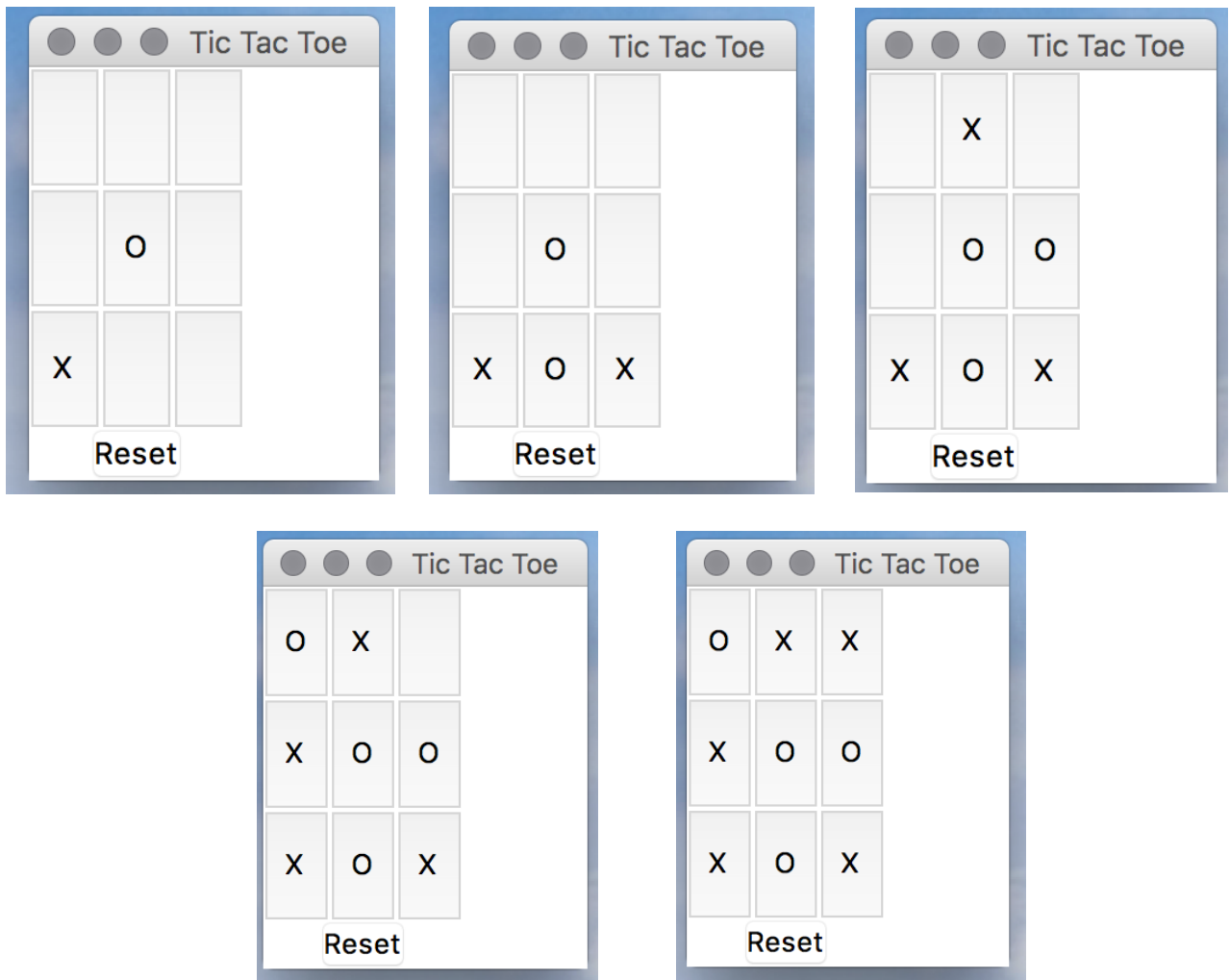
### 2 Game

All examples and codes that I saw in internet were about either deep reinforcement learning or using basic methods. At the beginning of the project, I wanted to make a backgammon game which has both dice and place variables. So I decided to make a Tic Tac Toe game.

#### 2.1 Tic Tac Toe

In our game, Tic Tac Toe, at each discrete time step  $t$ , the state  $s$  of the system is defined by the signs X and O at the board and which player's turn it is, and the possible actions  $a$  by the empty places at the board. It is important finding a policy that states belong to action which tells us which action to take in which state to maximize our chance of winning.

At any given time each state has a specific value  $V$  to the  $pi$ , which is the expected reward from following policy for all future time: where  $r_t = r_t(s_t, a_t)$  is the reward at time step  $t$  and  $\Gamma$  represents  $\Gamma$ , discount factor.



In the implementation of Tic Tac Toe, 'sign convention' is important. For player "X", our reward is positive -- specifically, a reinforcement of 1.0 is awarded when player "X" wins, -1.0 when player "O" wins, and 0.5 in the case of a tie. Therefore, player "X" aims to maximize the value, while player "O" aims to minimize it. The discount factor Gamma is given a value of 0.9.

## References

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